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Fast Fine-Grained Air Quality Index Level Prediction Using Random Forest Algorithm on Cluster Computing of Spark

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Outline

1. Introduction 
2. Implementation of Radom Forests Algorithm on Spark
3. Experiment & Results Analysis
4. Conclusion

Background



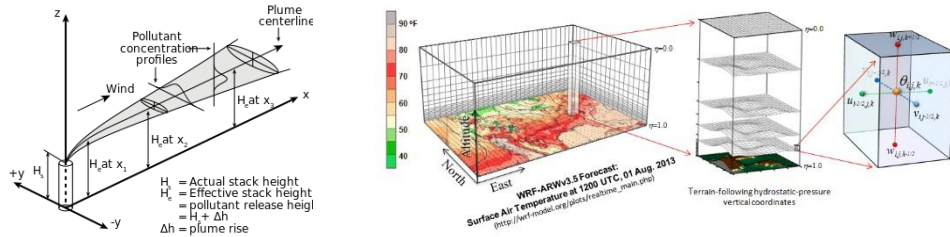
- What are the pollutants in the air?
 - NO₂/SO₂/PM_{2.5}/PM₁₀
- Why it matters?
 - 1 in 8 deaths linked to air pollution (WHO)
- Reality
 - Building an air quality monitor station is difficulty



All pictures are from Google-- www.google.com

Challenges

Traditional methods do not work well



Gaussian plume model Community Multi-scale Air Quality model

Difficult to decide the application conditions and many key parameters are arduous to obtain

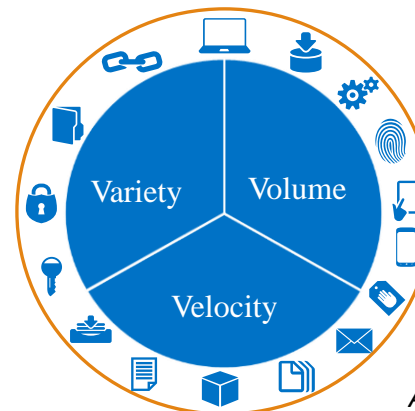


Limited to a few gasses: CO₂ and CO
 Sensors for detecting aerosol are not portable: PM₁₀
 A long period of sensing process, 1-2 hours

New techniques are facing big data challenges



Data mining and machine learning techniques play a critical role in air quality index prediction



- ✓ Millions even billions records in DB
- ✓ Data is generated quickly
- ✓ Many kinds of data can be used to predict AQI

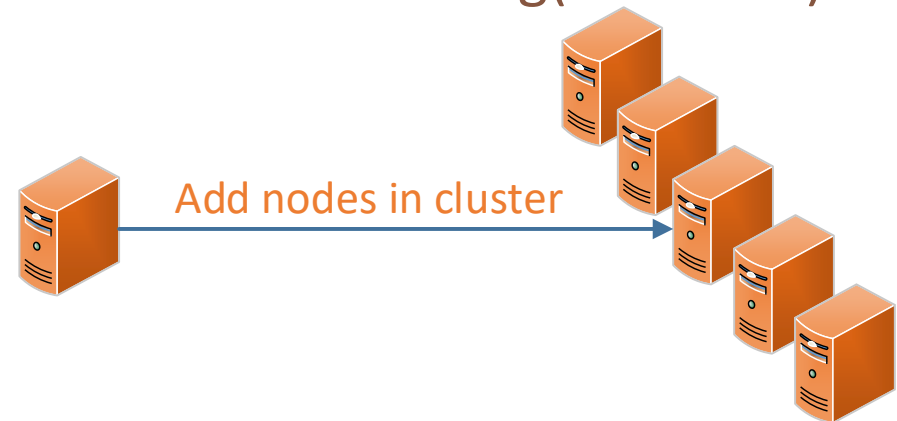
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How to deal with the big data challenges in AQI prediction?

Vertical scaling(scale-up)



Horizontal scaling(scale-out)



- Optimal data structure design(Hash/RB Tree)
- Parallel programming(OpenMP/MPI)
- Fault tolerance, concurrency
- Distributed platforms like Apache Hadoop and Spark

We focus on the **design and implementation of traditional random forests algorithm based on Apache Spark** and use this algorithm to do AQI prediction, at last, we test the algorithm's **scalability** when deal with big data set.

Outline

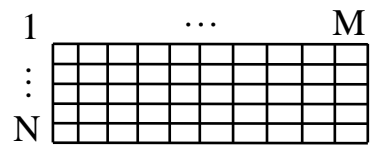
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Random forests algorithm

- Random forests are an ensemble classifier that consists of many decision trees, and output the class that is the mode of the output by individual trees--CART.

Random sample



- ✓ Row: sample N with replacement
- ✓ Column: sample m attributes without replacement ($m = \sqrt{M}$)

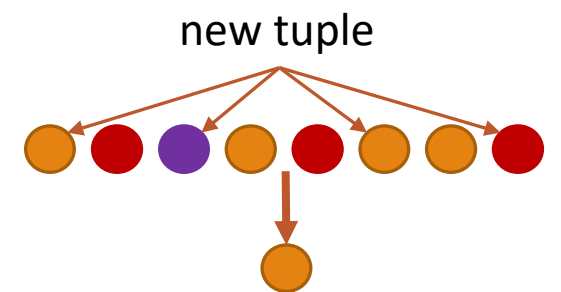
Impurity measurement

$$Gini(D) = 1 - \sum_{i=1}^k \left(\frac{|C_i|}{|D|}\right)^2$$

$$Gini_A(D) = \frac{|D_1|}{|D|} Gini(D_1) + \frac{|D_2|}{|D|} Gini(D_2)$$

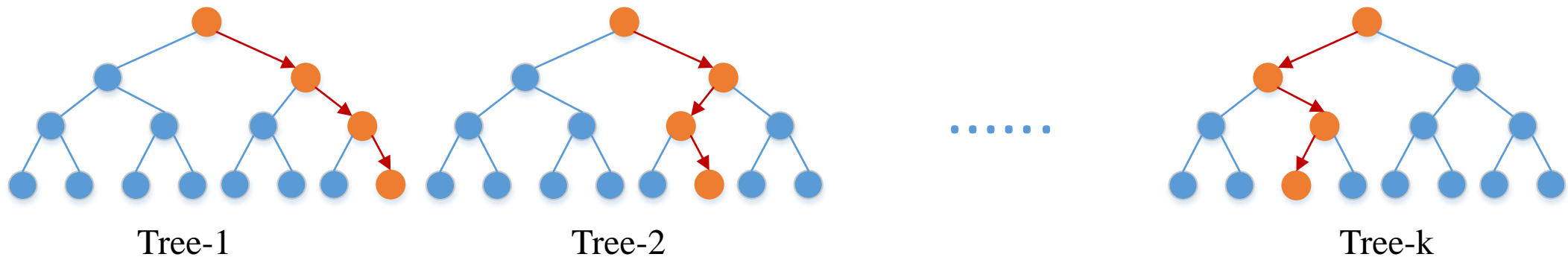
- ✓ The attribute that with the minimum Gini index is selected as the splitting attribute

Vote of classifiers



- ✓ Classification that has the most votes is the final prediction

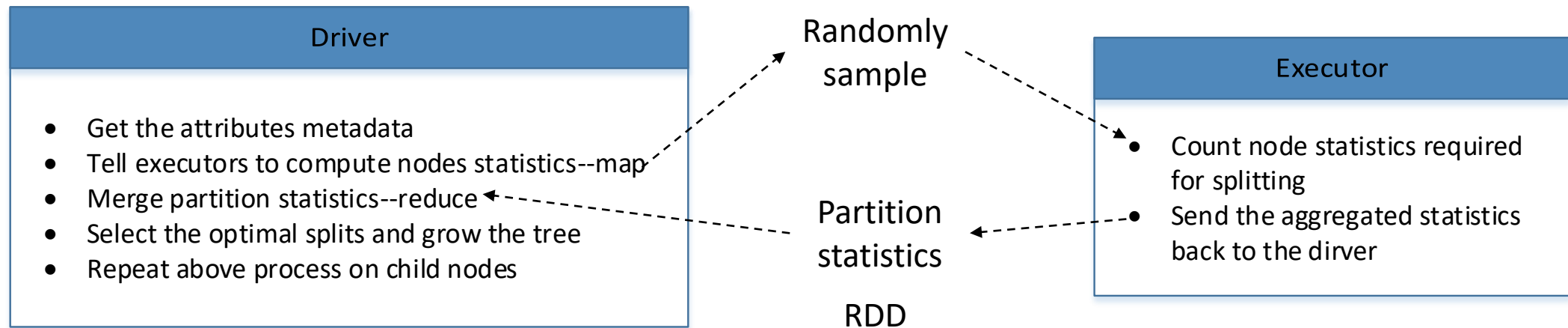
Advantages



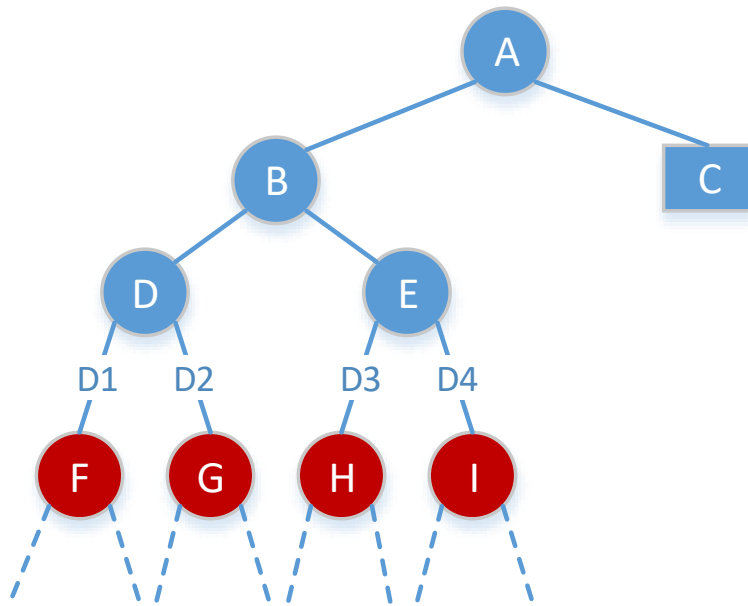
- It is one of the most **accurate** learning algorithms available.
- It gives estimates of **what variables are important** in the classification.
- It has an effective method for estimating **missing data** and maintains accuracy when a large proportion of the data is missing.

Distributed tree training in Spark

- The idea is from Google' PLANET (Parallel Learner for Assembling Numerous Ensemble Trees) and Sequoia Forest.
- Individual trees are built node by node and level by level in the driver node.
- At each iteration, individual executors compute partition statistics that is required to determine node splits.



Map and Reduce



■ Mappers:

- ✓ For each node store statistics of the data entering the node

$$\langle \text{NodeID}, |C_k|, |D_n|, k \rangle$$

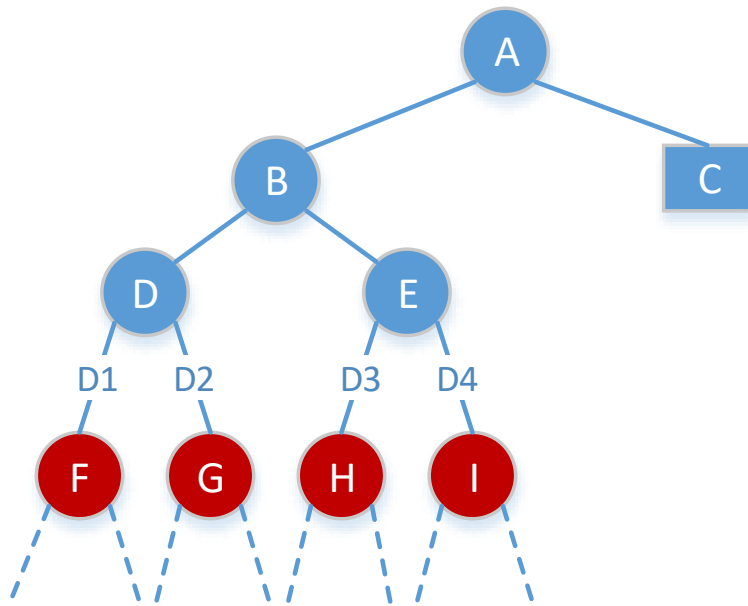
For example: $\langle F, |C_1|, |C_2|, |D| = 100, k = 2 \rangle$

- ✓ For each split store statistics

$$\langle \text{NodeID}, \text{Split}, |C_k|, |D_n|, k \rangle$$


For example: $\langle F, A_1 < 3, |C_1|, |C_2|, |D| = 20, k = 2 \rangle$

Map and Reduce

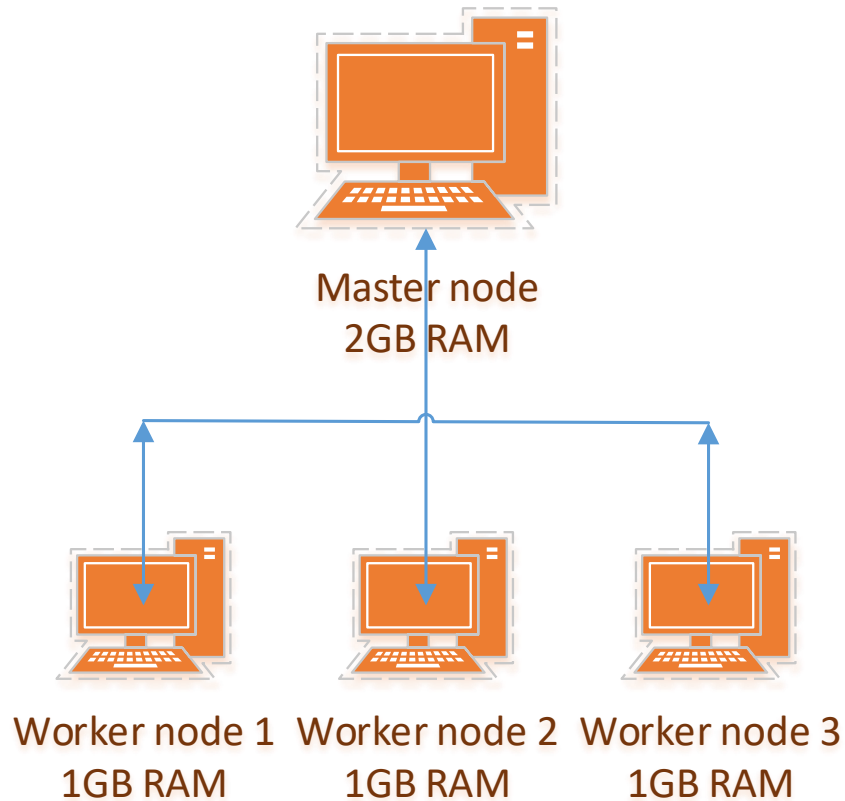


- Reducers:
 - ✓ Load all the $\langle \text{NodeID}, |C_k|, |D_n|, k \rangle$ pairs and aggregate per node statistics.
 - ✓ Load all the $\langle \text{NodeID}, \text{Split}, |C_k|, |D_n|, k \rangle$ data and aggregate every possible split statistics.
 - ✓ For each NodeID, output the best split (locally).
- Driver
 - ✓ Collects outputs from all reducers $\langle \text{split.NodeID}, \text{attribute}, \text{value}, \text{Impurity} \rangle$, for each node decides the best split(globally).
 - ✓ If D^* is small enough, build the subtree locally on driver to speed up the whole process. Else run map and reduce jobs.

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Experiment environment and data set description



Configuration of a 4-node cluster

- A 4-node cluster.
- The data set comes from the public data source of MSRA. It is comprised of 1 year 36 air quality monitor stations' data of Beijing.

| Temperature | Weather | Wind | Pressure | Humidity | PM2.5 |
|-------------|---------|------|----------|----------|-------|
| -5 | Sunny | 3 | 1031 | 46 | M |

- There are six class labels, {Good, Moderate, Unhealthy for Sensitive, Unhealthy, Very Unhealthy, Hazardous}.
- We use the former 5 attributes to predict the level of PM2.5.

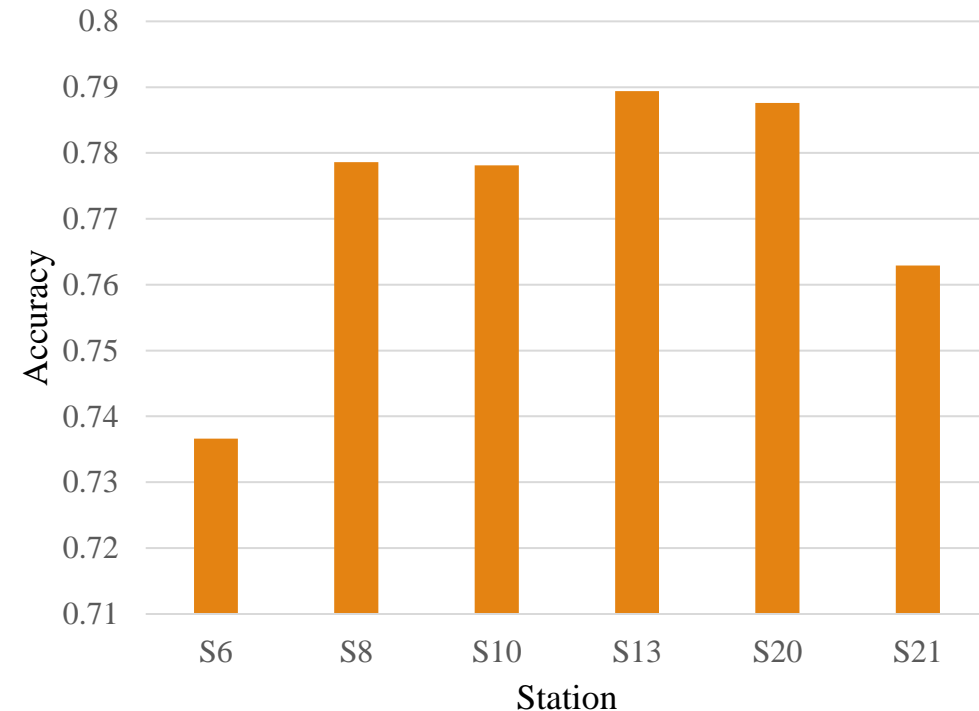
Experimental results

Confusion matrix

| Truth | Predictions | | | | | Recall |
|-------|-------------|--------|--------|--------|--------|--------|
| | G | M | US | U | VU&H | |
| G | 1088 | 157 | 13 | 3 | 2 | 0.8614 |
| M | 169 | 755 | 237 | 27 | 11 | 0.6297 |
| US | 10 | 98 | 966 | 278 | 26 | 0.7012 |
| U | 10 | 38 | 72 | 1584 | 184 | 0.8390 |
| VU&H | 5 | 1 | 3 | 59 | 964 | 0.9341 |
| | 0.8487 | 0.7197 | 0.7483 | 0.8112 | 0.8121 | 0.7925 |
| | Precision | | | | | |

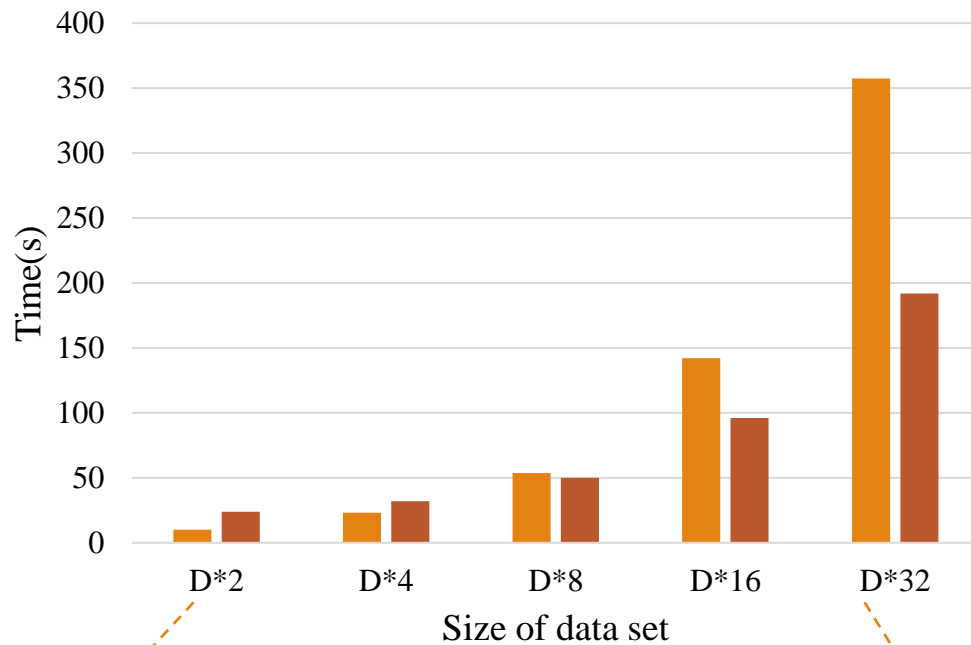
- In the DB, we select one of the 36 stations and it's data as test dataset, and the other stations data as training set.
- The accuracy is about 0.79, all the precisions in prediction are above 0.7.

Results of different tests



Scalability for big data

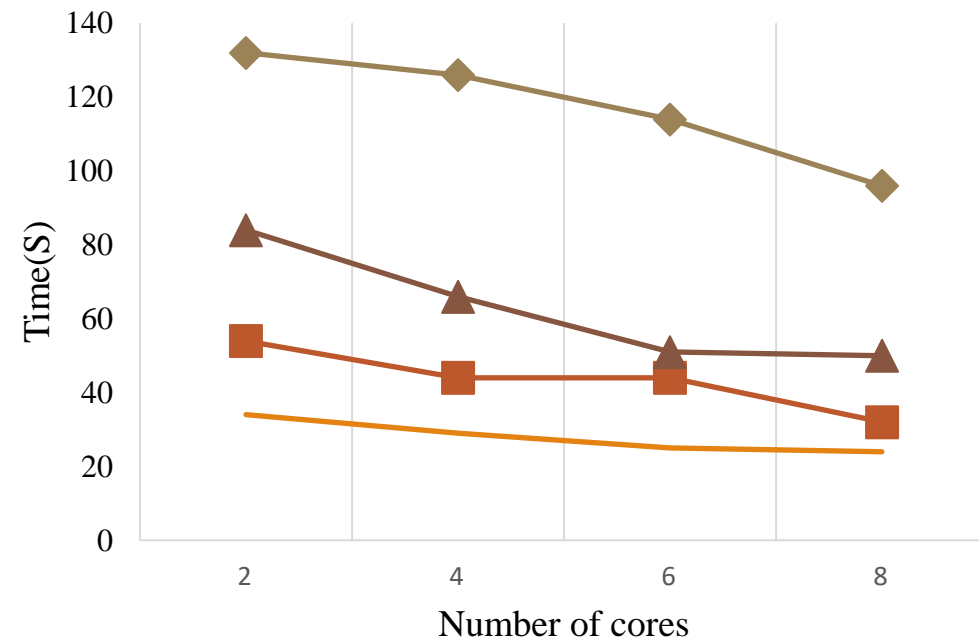
Standalone-RF VS Spark-RF




3 million

108 million

Execution time with different cores



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Conclusion

- This paper investigated a fast parallelized AQI level prediction method using random forests algorithm on Apache Spark. The individual trees are built node by node and level by level. Besides, a locally sub-tree building scheme is used to accelerate the processing speed.
- Experimental results showed that the parallelized random forests algorithm achieved relatively high accuracy in prediction. The results also proved the algorithm's effectiveness and efficiency when dealing with big data set.



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Thanks for your attention!
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